

EE331 Signals and Systems

Lecture 3

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1. Complex Function of a Real Variable

2. Exponential and Sinusoidal Signals

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3.1 DT unit impulse and unit step functions

3.2 CT unit impulse and unit step functions

Complex Function

Complex function

$$f : G \subset \mathbb{C} \rightarrow \mathbb{C}$$
$$z \mapsto f(z)$$

Four kinds of complex functions

1. **real** function of a **real** variable

▶ studied in calculus. e.g. $f(t) = e^t, t \in \mathbb{R}$

2. **complex** function of a **real** variable

▶ current focus. e.g. $f(t) = e^{i2\pi t}, t \in \mathbb{R}$

3. **real** function of a **complex** variable

▶ e.g. $f(z) = |z|, z \in \mathbb{C}$

4. **complex** function of a **complex** variable

▶ later, e.g. $f(z) = e^z, z \in \mathbb{C}$

Complex Function of a Real Variable

$$f : G \subset \mathbb{R} \rightarrow \mathbb{C}$$
$$t \mapsto f(t)$$

Equivalent to two real functions of a real variable

$$f(t) = u(t) + jv(t) \iff \begin{cases} u(t) = \operatorname{Re}f(t) \\ v(t) = \operatorname{Im}f(t) \end{cases}$$

e.g.

$$f(t) = e^{j2\pi t} \iff \begin{cases} u(t) = \cos(2\pi t) \\ v(t) = \sin(2\pi t) \end{cases}$$

Complex Function of a Real Variable

Calculus of $f(t) = u(t) + jv(t)$

Limit

$$\lim_{t \rightarrow t_0} f(t) = \lim_{t \rightarrow t_0} u(t) + j \lim_{t \rightarrow t_0} v(t)$$

Continuity

$f(t)$ continuous $\iff u(t)$ and $v(t)$ continuous

Differentiation

$$f'(t) = u'(t) + jv'(t)$$

Integration

$$\int f(t) dt = \int u(t) dt + j \int v(t) dt$$

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2.2 DT complex exponential and sinusoidal signals

3. Unit Impulse and Unit Step Functions

3.1 DT unit impulse and unit step functions

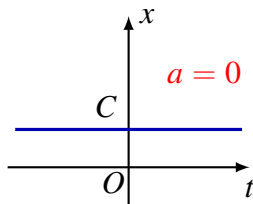
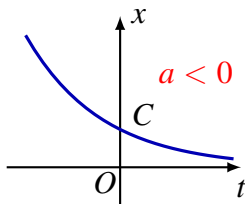
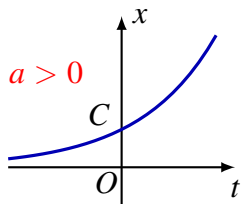
3.2 CT unit impulse and unit step functions

CT Complex Exponential Signals

$$x(t) = Ce^{at}, \quad \text{where } C \in \mathbb{C}, a \in \mathbb{C}$$

Real exponential signals: $C \in \mathbb{R}, a \in \mathbb{R}$

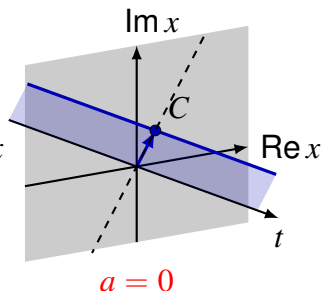
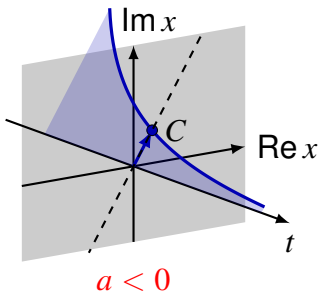
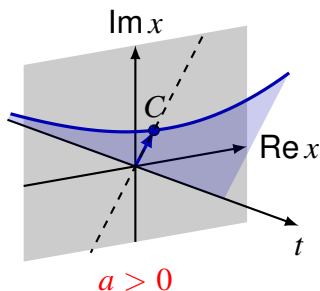
1. $a > 0$: growing exponential
2. $a < 0$: decaying exponential
3. $a = 0$: constant



CT Complex Exponential Signals

$$x(t) = Ce^{at}, \quad \text{where } C \in \mathbb{C}, a \in \mathbb{R}$$

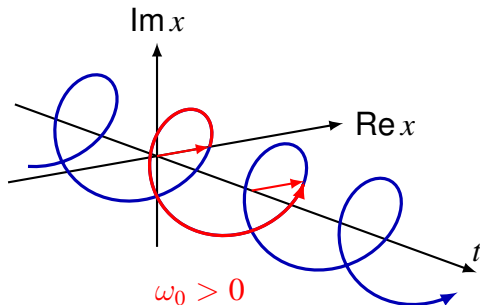
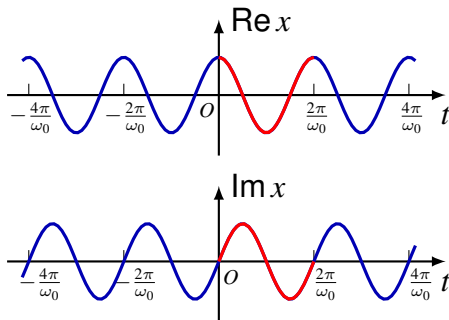
1. $a > 0$: diverges from t axis, $|x(t)| \nearrow \infty$ as $t \rightarrow \infty$
2. $a < 0$: converges to t axis, $|x(t)| \searrow 0$ as $t \rightarrow \infty$
3. $a = 0$: constant



CT Complex Exponential Signals

Periodic complex exponential signals

$$x(t) = e^{j\omega_0 t} = \cos(\omega_0 t) + j \sin(\omega_0 t), \quad \text{where } \omega_0 \in \mathbb{R}$$



(Angular) frequency: ω_0 radians/s

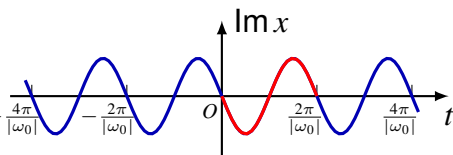
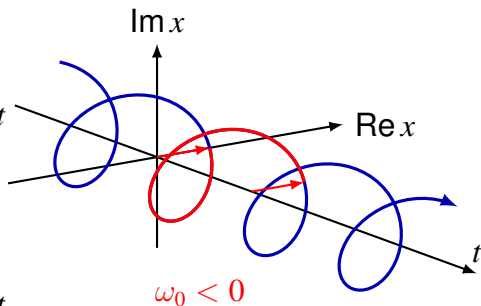
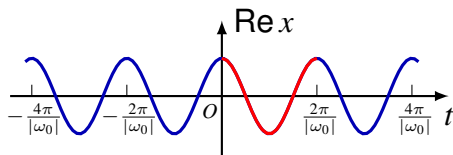
Frequency: $f_0 = \omega_0 / (2\pi)$ cycles/s, Hz

Fundamental period: $T_0 = 2\pi / |\omega_0| = 1 / |f_0|$ s (**only if** $\omega_0 \neq 0$)

CT Complex Exponential Signals

Periodic complex exponential signals

$$x(t) = e^{j\omega_0 t} = \cos(|\omega_0|t) - j \sin(|\omega_0|t), \quad \text{where } \omega_0 < 0$$

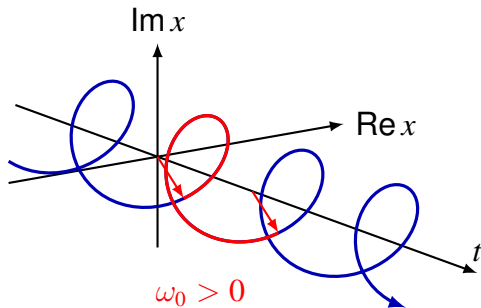
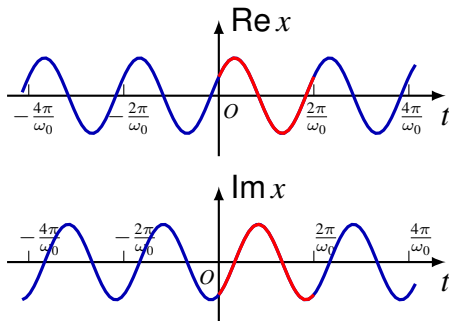


Fundamental frequency: $|\omega_0|$, $|f_0|$

CT Complex Exponential Signals

Periodic complex exponential signals

$$x(t) = Ce^{j\omega_0 t} = |C| \cos(\omega_0 t + \phi) + j \sin(\omega_0 t + \phi), \quad \text{where } C = |C|e^{j\phi}$$



CT Complex Exponential Signals

Sinusoidal signals

$$x(t) = A \cos(\omega_0 t + \phi), \quad A \in \mathbb{R}$$

Conversion between exponentials and sinusoids

$$Ae^{j(\omega_0 t + \phi)} = A \cos(\omega_0 t + \phi) + jA \sin(\omega_0 t + \phi)$$

$$A \cos(\omega_0 t + \phi) = \frac{A}{2} e^{j\phi} e^{j\omega_0 t} + \frac{A}{2} e^{-j\phi} e^{-j\omega_0 t} = A \cdot \operatorname{Re} e^{j(\omega_0 t + \phi)}$$

$$A \sin(\omega_0 t + \phi) = A \cdot \operatorname{Im} e^{j(\omega_0 t + \phi)}$$

Same periodicity

- always periodic with fundamental frequency $|\omega_0|$
- larger $|\omega_0|$, faster oscillation

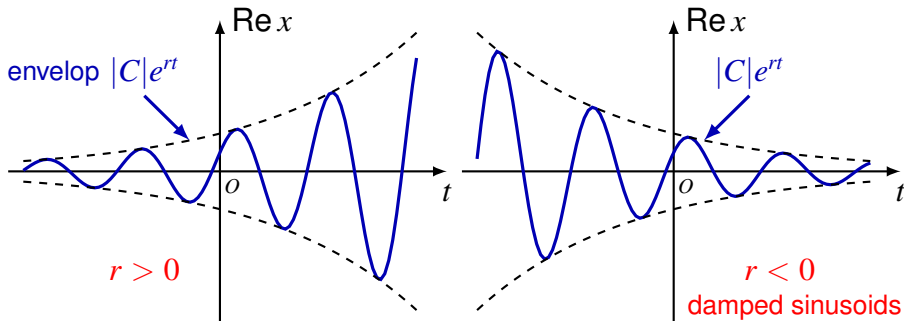
CT Complex Exponential Signals

General Complex Exponential Signals

$$x(t) = Ce^{at}, \quad \text{where } C = |C|e^{j\phi}, a = r + j\omega_0$$

↓

$$x(t) = |C|e^{rt}e^{j(\omega_0 t + \phi)} = |C|e^{rt} \cos(\omega_0 t + \phi) + j|C|e^{rt} \sin(\omega_0 t + \phi)$$

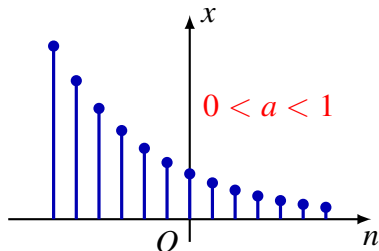
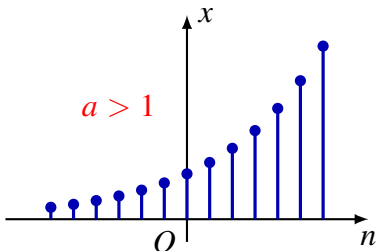


DT Complex Exponential Signals

$$x[n] = C\alpha^n = Ce^{\beta n}, \quad \text{where } C \in \mathbb{C}, \alpha = e^{\beta} \in \mathbb{C}$$

Real exponential signals: $C \in \mathbb{R}, \alpha \in \mathbb{R}$ (**but $\beta \in \mathbb{C}$!**)

1. $\alpha > 1$: monotonically growing
2. $0 < \alpha < 1$: monotonically decaying
3. $\alpha = 1$: constant

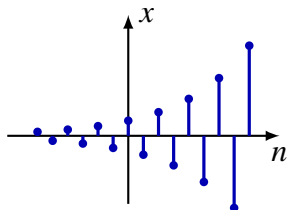


DT Complex Exponential Signals

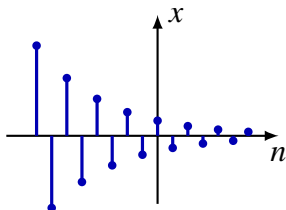
$$x[n] = C\alpha^n = Ce^{\beta n}, \quad \text{where } C \in \mathbb{C}, \alpha = e^{\beta} \in \mathbb{C}$$

Real exponential signals: $C \in \mathbb{R}, \alpha \in \mathbb{R}$ (**but** $\beta \in \mathbb{C}$!)

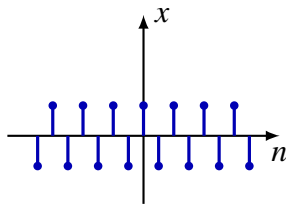
4. $\alpha < -1$: growing magnitude, alternating sign
5. $-1 < \alpha < 0$: decaying magnitude, alternating sign
6. $\alpha = -1$: constant magnitude, alternating sign ($\beta = j\pi$)



$$\alpha < -1$$



$$-1 < \alpha < 0$$



$$\alpha = -1$$

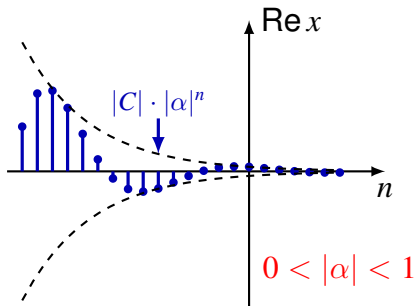
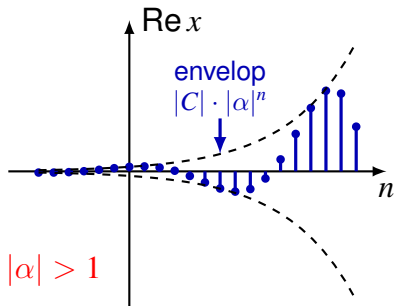
DT Complex Exponential Signals

General Complex Exponential Signals

$$x[n] = C\alpha^n, \quad \text{where } C = |C|e^{j\phi}, \alpha = |\alpha|e^{j\omega_0}$$

↓

$$x[n] = |C| \cdot |\alpha|^n e^{j(\omega_0 n + \phi)} = |C| \cdot |\alpha|^n \cos(\omega_0 n + \phi) + j|C| \cdot |\alpha|^n \sin(\omega_0 n + \phi)$$



DT Complex Exponential Signals

Sinusoidal Signals

$$x[n] = |C|e^{j(\omega_0 n + \phi)} = |C| \cos(\omega_0 n + \phi) + j|C| \sin(\omega_0 n + \phi)$$

Periodicity

- periodic $\iff \omega_0 = 2\pi \frac{k}{N}$ for $k \in \mathbb{Z}, N \in \mathbb{Z}_+$
- fundamental period $N_0 = N / \gcd(N, k)$

Fundamental frequency

- zero if $N_0 = 1$
- $2\pi/N_0$ if $N_0 > 1$

Example. $x[n] = e^{j3\pi n}$ has $N_0 = 2$, fundamental frequency π , **not 3π !** Note $e^{j3\pi n} = e^{j\pi n}$.

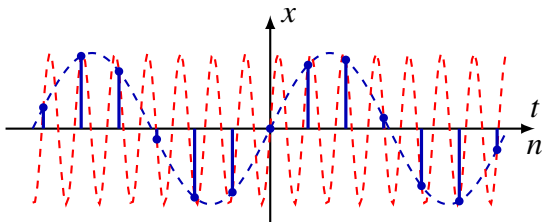
DT Complex Exponential Signals

Aliasing

- $e^{j\omega_1 t} = e^{j\omega_2 t}, \forall t \in \mathbb{R} \iff \omega_1 = \omega_2$
- $e^{j\omega_1 n} = e^{j\omega_2 n}, \forall n \in \mathbb{N} \iff \omega_1 = \omega_2 + 2k\pi, k \in \mathbb{Z}$

frequencies differing by $2k\pi$ yields same discrete sinusoid

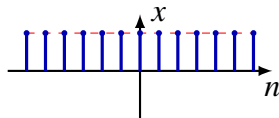
Example. $\omega_1 = 1, \omega_2 = 1 + 2\pi$



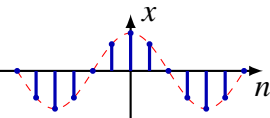
For DT signals, suffices to consider frequencies on an interval of length 2π , e.g. $[0, 2\pi)$ or $(-\pi, \pi]$

DT Complex Exponential Signals

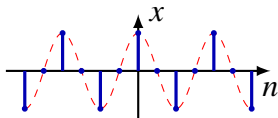
High frequencies around $(2k + 1)\pi$, low frequencies around $2k\pi$



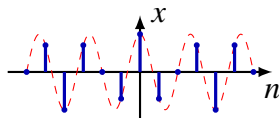
$$x[n] = \cos(0 \cdot n) = 1$$



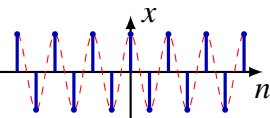
$$x[n] = \cos(\pi n/4)$$



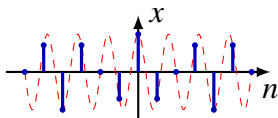
$$x[n] = \cos(\pi n/2)$$



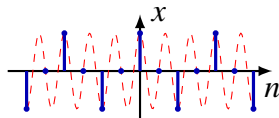
$$x[n] = \cos(3\pi n/4)$$



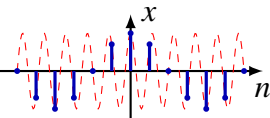
$$x[n] = \cos(\pi n)$$



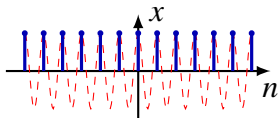
$$x[n] = \cos(5\pi n/4)$$



$$x[n] = \cos(3\pi n/2)$$



$$x[n] = \cos(7\pi n/4)$$



$$x[n] = \cos(2\pi n) = 1$$

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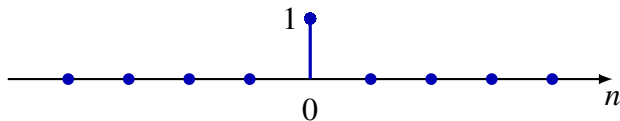
3. Unit Impulse and Unit Step Functions

3.1 DT unit impulse and unit step functions

3.2 CT unit impulse and unit step functions

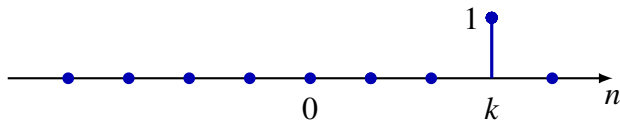
DT Unit Impulse (Unit Sample)

$$\delta[n] = \delta_{0n} = \begin{cases} 1, & n = 0 \\ 0, & n \neq 0 \end{cases}$$



Shifted version $\tau_k \delta$

$$\tau_k \delta[n] = \delta[n - k] = \delta_{kn} = \begin{cases} 1, & n = k \\ 0, & n \neq k \end{cases}$$



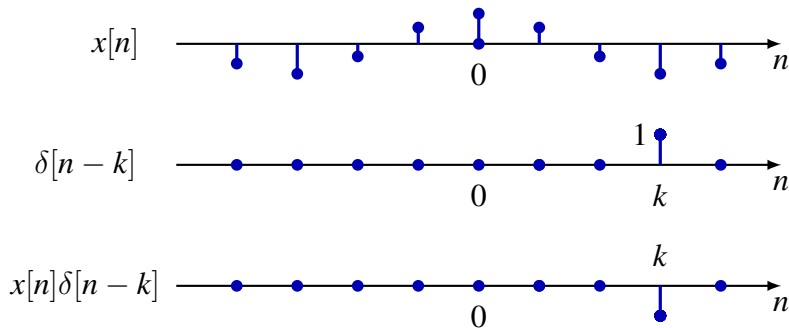
DT Unit Impulse (Unit Sample)

Sampling property

$$x\delta = x[0]\delta, \quad \text{or} \quad (x\delta)[n] = x[n]\delta[n] = x[0]\delta[n], \quad \forall n \in \mathbb{Z}$$

More generally,

$$x\tau_k\delta = x[k]\tau_k\delta, \quad \text{or} \quad x[n]\delta[n - k] = x[k]\delta[n - k], \quad \forall n \in \mathbb{Z}$$



DT Unit Impulse (Unit Sample)

Recall from linear algebra,

$$\mathbf{e}_k = (0, \dots, 0, \underset{\substack{\uparrow \\ k\text{-th}}}{1}, 0, \dots, 0)^T, \quad k = 1, 2, \dots, n$$

form basis of \mathbb{R}^n (and \mathbb{C}^n)

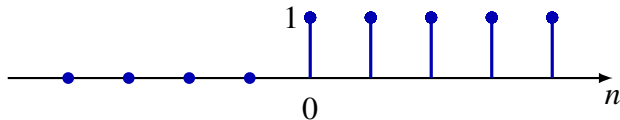
$$\mathbf{x} = (x_1, x_2, \dots, x_n)^T = \sum_{k=1}^n x_k \mathbf{e}_k$$

Similarly, $\{\tau_k \delta : k \in \mathbb{Z}\}$ is a basis of $\mathbb{C}^{\mathbb{Z}}$, space of doubly infinite sequences of complex numbers

$$x = \sum_{k=-\infty}^{\infty} x[k] \tau_k \delta, \quad \text{or} \quad x[n] = \sum_{k=-\infty}^{\infty} x[k] \delta[n - k], \quad \forall n \in \mathbb{Z}$$

DT Unit Step

$$u[n] = \begin{cases} 0, & n < 0 \\ 1, & n \geq 0 \end{cases}$$



Relation to unit impulse

$$u[n] = \sum_{k=0}^{\infty} \delta[n - k] = \sum_{m=-\infty}^n \delta[m] \quad \text{running sum}$$

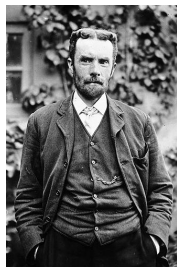
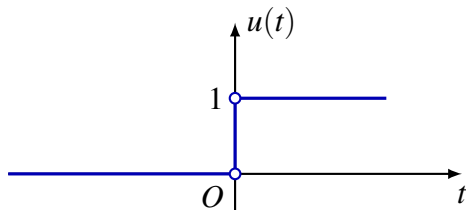
$$\delta[n] = u[n] - u[n - 1] \quad \text{first (backward) difference}$$

CT Unit Step Function

Also called Heaviside (step) function

$$u(t) = \begin{cases} 0, & t < 0 \\ 1, & t > 0 \end{cases}$$

- undefined at $t = 0$
- sometimes $u(0) = 0, 1, 1/2$



Oliver Heaviside
(from Wikipedia)

CT Unit Impulse Function

Also called **Dirac delta function** or δ function

$$\delta(t) = \frac{du}{dt}(t) = \lim_{\Delta \rightarrow 0} \delta_{\Delta}(t)$$

where

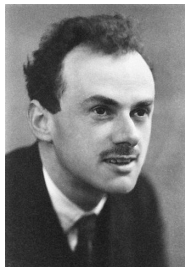
$$\delta_{\Delta}(t) = \frac{u(t + \frac{\Delta}{2}) - u(t - \frac{\Delta}{2})}{\Delta}$$

Physical models

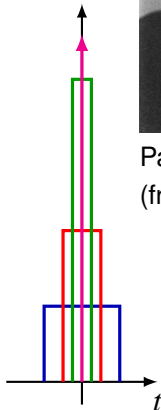
- density of point mass/charge
- impulse force

By calculus

$$\frac{du}{dt}(t) = \begin{cases} 0, & t \neq 0 \\ +\infty, & t = 0 \end{cases}$$



Paul Dirac
(from Wikipedia)



Specification of Function by Action

Classically, function is defined by specifying value at each point in its domain, e.g.

$$\begin{aligned}x &: \mathbb{R} \rightarrow \mathbb{R} \\ t &\mapsto x(t)\end{aligned}$$

Idea. Define function by “action” on “test functions”

Example in physics

- impulse force specified by change of momentum

Example in linear algebra

- Matrix $A \in \mathbb{R}^{n \times n}$
 - ▶ specify each entry A_{ij}
 - ▶ specify action $A\mathbf{x}$ for all vector $\mathbf{x} \in \mathbb{R}^n$

Specification of Function by Action

Let $C[a, b]$ denote set of continuous functions on $[a, b]$

Action of x on $\phi \in C[a, b]$

$$T_x[\phi] = \int_a^b x(t)\phi(t)dt \quad \text{functional on } C[a, b]$$

Lemma. Let $x_i(t) \in C[a, b]$, $i = 1, 2$.

$$T_{x_1}[\phi] = T_{x_2}[\phi], \quad \forall \phi \in C[a, b] \iff x_1 = x_2$$

Proof. \Leftarrow obvious. For \Rightarrow , let $\phi = \bar{x}_1 - \bar{x}_2$. Then

$$\int_a^b |x_1(t) - x_2(t)|^2 dt = 0 \implies |x_1(t) - x_2(t)|^2 = 0 \implies x_1 = x_2$$

Set of values $T_x[\phi]$, $\forall \phi \in C[a, b]$ uniquely determines x !

To determine x , instead of specifying $x(t)$ for all $t \in [a, b]$, specify $T_x[\phi]$ for all $\phi \in C[a, b]$.

Action of Unit Impulse Function

Define action of δ on ϕ by

$$\delta[\phi] = \left. \int_{-\infty}^{\infty} \delta(t)\phi(t)dt \right. \triangleq \lim_{\Delta \rightarrow \infty} T_{\delta_{\Delta}}[\phi]$$

for $\phi(t)$ **continuous at $t = 0$** .

1. Compute

$$T_{\delta_{\Delta}}[\phi] = \int_{-\infty}^{\infty} \delta_{\Delta}(t)\phi(t)dt = \frac{1}{\Delta} \int_{-\Delta/2}^{\Delta/2} \phi(t)dt$$

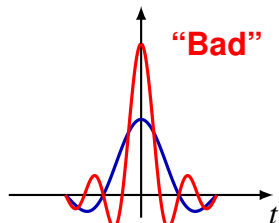
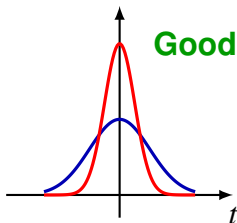
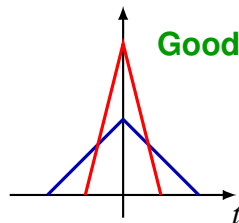
2. Let $\Delta \rightarrow 0$

$$\phi \text{ continuous at } 0 \implies \lim_{\Delta \rightarrow 0} T_{\delta_{\Delta}}[\phi] = \phi(0)$$

Defining property of δ : $\delta[\phi] \triangleq \int_{-\infty}^{\infty} \delta(t)\phi(t)dt = \phi(0)$

Other Approximations

Can define δ as limit of other functions.



$$g_{\Delta}(t) = \frac{1}{\sqrt{2\pi\Delta}} e^{-\frac{t^2}{2\Delta^2}}$$

$$D_{\Delta}(t) = \frac{\sin\left(\frac{\pi t}{\Delta}\right)}{\pi t}$$

Family $\{K_{\Delta}(t)\}_{\Delta>0}$ called **good kernels** or **approximation to the identity** if

1. For all $\Delta > 0$, $\int_{-\infty}^{\infty} K_{\Delta}(t) dt = 1$
2. For some $M > 0$ and all $\Delta > 0$, $\int_{-\infty}^{\infty} |K_{\Delta}(t)| dt < M$
3. For every $\epsilon > 0$, $\lim_{\Delta \rightarrow 0} \int_{|t|>\epsilon} |K_{\Delta}(t)| dx = 0$

Properties of Unit Impulse Function

Unit “area”

$$\int_{-\infty}^{\infty} \delta(\tau) d\tau = 1$$

Proof. Let $\phi(t) = 1$ in defining property.

Integration

$$u(t) = \int_{-\infty}^t \delta(\tau) d\tau$$

Proof. Let $\phi_t(\tau) = u(t - \tau)$. For $t \neq 0$, ϕ_t is continuous at $\tau = 0$. By defining property,

$$\int_{-\infty}^t \delta(\tau) d\tau = \int_{-\infty}^{\infty} \delta(\tau) \phi_t(\tau) d\tau = \phi_t(0) = u(t)$$

Transformations of Unit Impulse

Defined s.t. usual rules for change of variables hold

Time scaling $(S_a\delta)[\phi] \triangleq \delta[a^{-1}S_{a^{-1}}\phi]$, where $a > 0$

$$\int_{-\infty}^{\infty} \delta(at)\phi(t)dt \triangleq \int_{-\infty}^{\infty} \delta(t)\phi\left(\frac{t}{a}\right)\frac{dt}{a} \implies \delta(at) = \frac{1}{a}\delta(t)$$

Time reversal $(R\delta)[\phi] \triangleq \delta[R\phi]$

$$\int_{-\infty}^{\infty} \delta(-t)\phi(t)dt \triangleq \int_{-\infty}^{\infty} \delta(t)\phi(-t)dt \implies \delta(-t) = \delta(t)$$

Time shift $(\tau_a\delta)[\phi] \triangleq \delta[\tau_{-a}\phi]$

$$\int_{-\infty}^{\infty} \delta(t-a)\phi(t)dt \triangleq \int_{-\infty}^{\infty} \delta(t)\phi(t+a)dt = \phi(a)$$

Multiplication and Sampling Property

Multiplication by ordinary function $(x\delta)[\phi] = \delta[x\phi]$

$$\int_{-\infty}^{\infty} [x(t)\delta(t)]\phi(t)dt \triangleq \int_{-\infty}^{\infty} \delta(t)[x(t)\phi(t)]dt = x(0)\phi(0)$$

Sampling property

$$x\delta = x(0)\delta, \quad \text{or} \quad x(t)\delta(t) = x(0)\delta(t)$$

Proof.

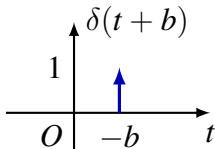
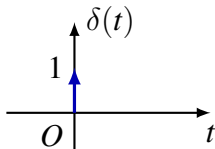
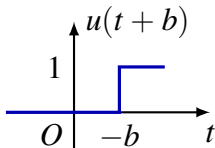
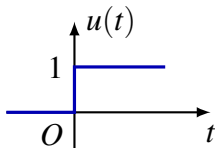
$$(x\delta)[\phi] = \delta[x\phi] = x(0)\phi(0) = x(0)\delta[\phi] = (x(0)\delta)[\phi]$$

Derivatives of $u(at + b)$ and $x(t)u(t)$

Chain rule holds

$$\frac{d}{dt}u(t + b) = \delta(t + b)$$

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Leibniz rule holds

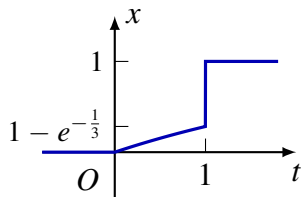
$$[x(t)u(t)]' = x'(t)u(t) + x(0)\delta(t)$$

Will see later general procedure for taking derivatives.

Functions with Jump Discontinuities

Example.

$$\begin{aligned}x(t) &= (1 - e^{-\frac{1}{3}t})[u(t) - u(t - 1)] + u(t - 1) \\ &= \begin{cases} 0, & t < 0 \\ 1 - e^{-t/3}, & 0 < t < 1 \\ 1, & t > 1 \end{cases}\end{aligned}$$



$$x'(t) = \frac{1}{3}e^{-\frac{1}{3}t}[u(t) - u(t - 1)] + e^{-\frac{1}{3}}\delta(t - 1)$$

1. impulse at each discontinuity
2. impulse size equal to jump size

