

Lecture 1. Introduction

Mathematical optimization problem

minimize $f(x)$

subject to $x \in \Omega$

where $f: \mathbb{R}^n \rightarrow \mathbb{R}$ objective function 目标函数

$x = (x_1, \dots, x_n)^T \in \mathbb{R}^n$ optimization variables.

$\Omega \subseteq \mathbb{R}^n$ feasible set / constraint set

- $x \in \Omega$ feasible 可行 infeasible o.w.

- Ω specified by constraint functions g_1, \dots, g_m .

$\min_x f(x)$

s. t. $g_i(x) \leq 0, \quad i=1, \dots, m.$

x^* : optimal solution. $f(x)$ achieves optimal.

$x^* = \operatorname{argmin} f(x).$

Remark: maximizing $f(x)$ is equivalent to minimizing $-f(x)$

why linear and convex?

In general optimization problems are very difficult to solve.

Knapsack problem. 背包问题

n types of knapsacks.

i^{th} type carry a_i pencils and b_i books. costs c_i

A pencils and B books in total.

Goal: spend least money.

$$\min \sum_i c_i x_i$$

$$\text{s.t. } \sum_i a_i x_i \geq A$$

$$\sum_i b_i x_i \geq B.$$

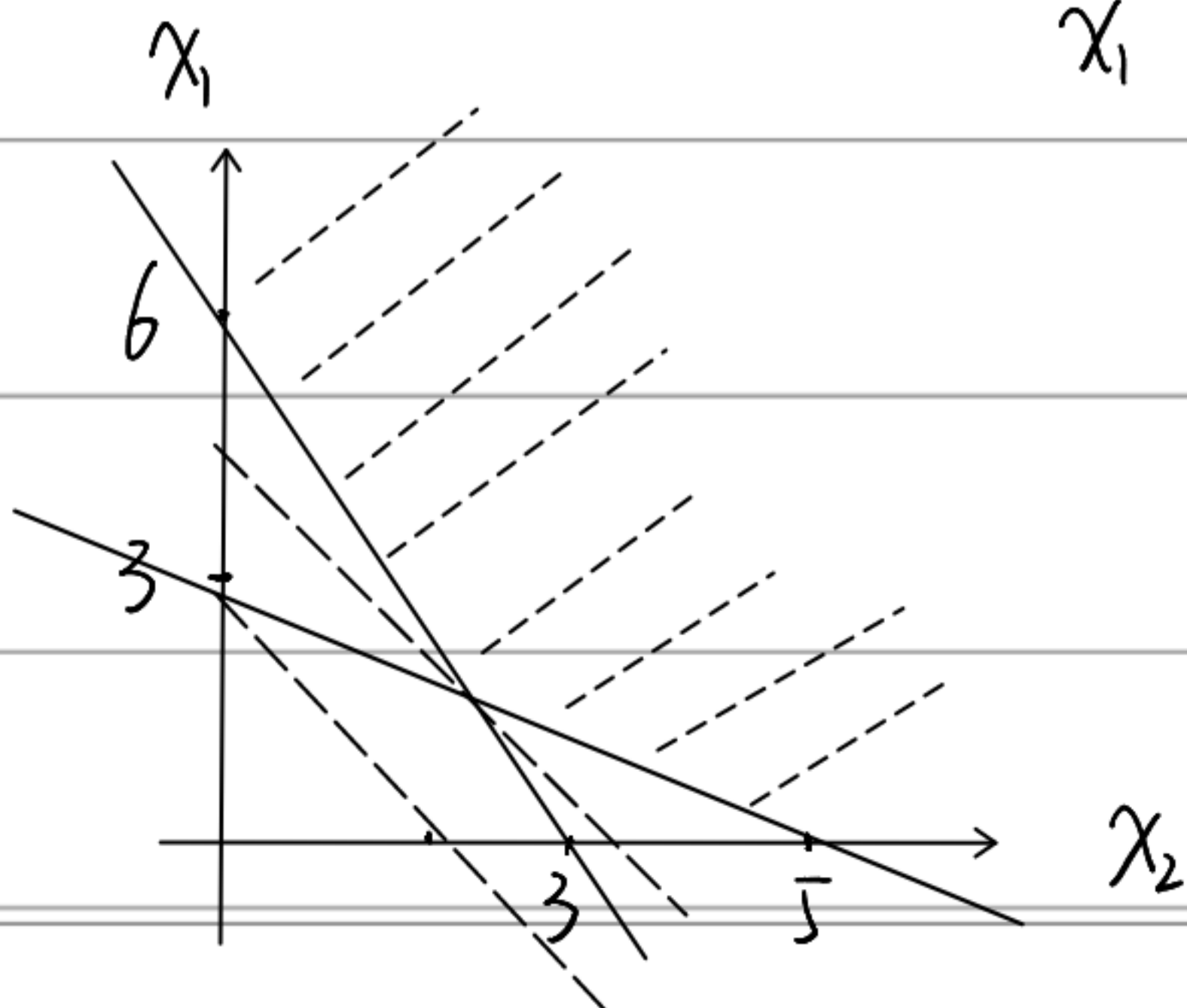
How to solve it?

if only 2 types.

$$\min 10x_1 + 15x_2.$$

$$\text{s.t. } 5x_1 + 3x_2 \geq 15$$

$$x_1 + 2x_2 \geq 6$$



more types?

simplex algorithm.

primal dual

Data fitting.

T	V
30	1.011
40	1.019
50	1.032
60	1.041
...	...

$$\begin{array}{c} V \\ \downarrow \\ y = kx + b. \end{array} \quad \begin{array}{c} T \\ \downarrow \end{array}$$

what are the two coefficient
k and b ?

Least squares method.

given n measurements.

$(x_1, y_1), \dots, (x_n, y_n).$

assume i^{th} error
denoted by $\epsilon_i.$

least squares criterion

minimize

$$\sum \epsilon_i = \sum (y_i - kx_i - b)^2$$

Geometric explanation : projection

$$\begin{cases} 30k + b = 1.011 \\ 40k + b = 1.019 \\ 50k + b = 1.032 \end{cases}$$

$$k \begin{bmatrix} 30 \\ 40 \\ 50 \end{bmatrix} + b \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = ?$$

projection of $\begin{bmatrix} 1.011 \\ 1.019 \\ 1.032 \end{bmatrix}$ onto the subspace spanned by

minimize $\left\| \begin{bmatrix} 30 & 1 \\ 40 & 1 \\ 50 & 1 \end{bmatrix} \begin{bmatrix} k \\ b \end{bmatrix} - \begin{bmatrix} 1.011 \\ 1.019 \\ 1.032 \end{bmatrix} \right\|_2$ $\begin{bmatrix} 30 \\ 40 \\ 50 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

Norm. inner product. distance to hyperplane

not necessary \mathbb{R}^n
Fourier

IP: An inner product $\langle \cdot, \cdot \rangle$ is a function $S \times S \rightarrow \mathbb{R}$ s.t.

1. nonnegative $\langle x, x \rangle \geq 0$ $= 0$ iff $x = 0$

2. symmetric $\langle x, y \rangle = \langle y, x \rangle$

3. linearity $\langle sx, y \rangle = s \langle x, y \rangle$ (homogeneity)

$$\langle x+y, z \rangle = \langle x, z \rangle + \langle y, z \rangle \quad (\text{additivity})$$

if $\langle x, y \rangle = 0$ then x and y are called orthogonal. \perp 交.

Euclidean inner product space: $\langle x, y \rangle = x^T y = \sum x_i y_i$

$\|\cdot\|$

Norm: a norm is a function $\mathbb{R}^n \rightarrow \mathbb{R}$ s.t.

1. nonnegative $\|x\| \geq 0$ $= 0$ iff $x = 0$.

2. positive homogeneity $\|a x\| = |a| \|x\|$

3. triangle inequality $\|x+y\| \leq \|x\| + \|y\|$.

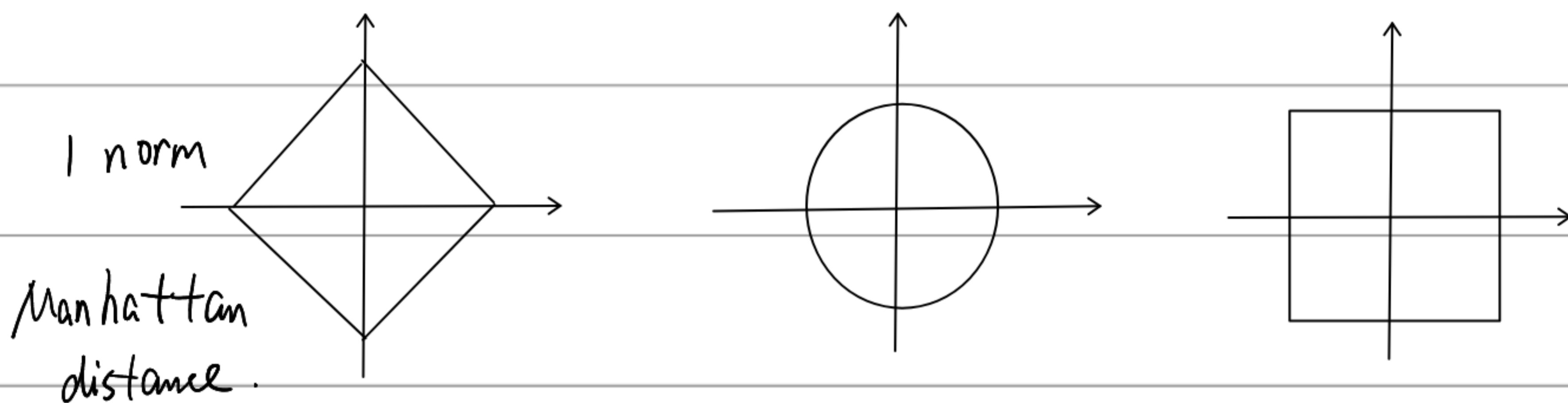
L^p -norm, or p -norm for real $p \geq 1$.

$$\|x\|_p = (|x_1|^p + |x_2|^p + \dots + |x_n|^p)^{1/p}$$

in particular. 1-norm: $\|x\|_1 = \sum_i |x_i|$

(Euclidean norm) 2: $\|x\| \stackrel{\Delta}{=} \|x\|_2 = \sqrt{\langle x, x \rangle} = \sqrt{\sum_i x_i^2}$
default

∞ -norm: $\|x\|_{\infty} = \max \{ |x_1|, |x_2|, \dots, |x_n| \}$.



Cauchy - Schwarz inequality

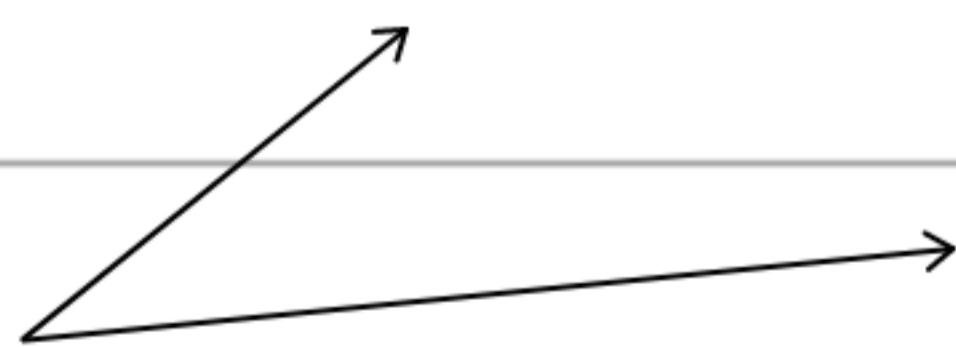
$$|\langle u, v \rangle|^2 \leq \langle u, u \rangle \cdot \langle v, v \rangle \quad \text{or.}$$

$$|\langle u, v \rangle| \leq \|u\| \|v\|.$$

n -dimensional Euclidean space. (\mathbb{R}^n)

$$\left(\sum_i u_i v_i \right)^2 \leq \left(\sum_i u_i^2 \right) \left(\sum_i v_i^2 \right).$$

Geometric explanation: projection.



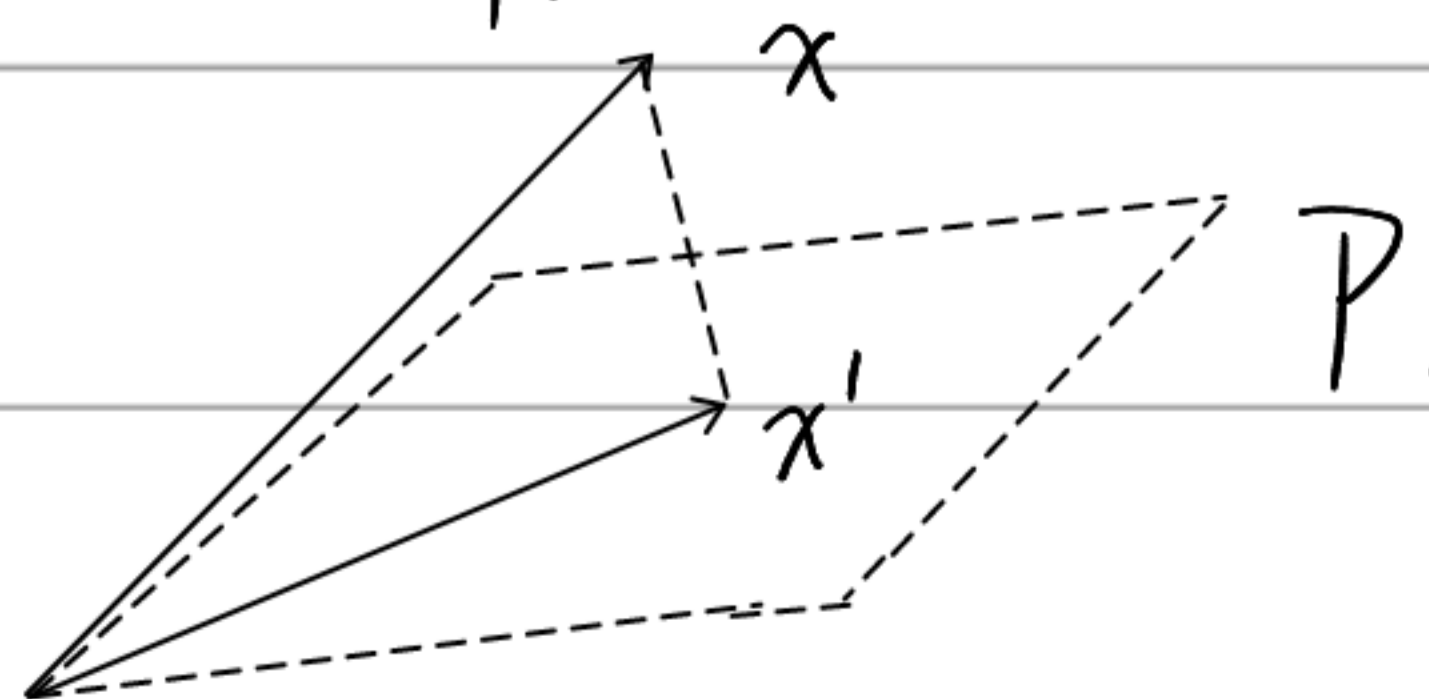
Distance to hyperplane.

hyperplane P : $w^T x + b = 0$

$w \perp P$.

orthogonal projection

$(x - x') \perp P \quad w^T x' + b = 0.$



$$x - x' = r \cdot w \text{ for some } r \in \mathbb{R}.$$

$$w^T (x - r \cdot w) + b = 0 \Rightarrow r = \frac{w^T x + b}{w^T w} \leftarrow \frac{1}{\|w\|^2}$$

distance from x to P is.

$$\min_{y \in P} \|x - y\| = \|x - x'\| = \|r w\| = \frac{|w^T x + b|}{\|w\|}$$

Linear least squares regression.

given m measurements $(x_1, y_1) \dots (x_m, y_m)$.

assume that $y = w^T x + b$.

The least squares regression is to compute the following opt.

$$\begin{aligned} & \min_{w \in \mathbb{R}^n, b \in \mathbb{R}} \sum_i (Xw + b \cdot \mathbf{1} - y)^2 \\ & = \min_{w \in \mathbb{R}^n, b \in \mathbb{R}} \|Xw + b \cdot \mathbf{1} - y\| \end{aligned}$$

where $X = (x_1, \dots, x_n)^T \in \mathbb{R}^{m \times n}$. $y = (y_1, \dots, y_m)^T \in \mathbb{R}^m$

$e \perp$ hyperspace spanned by column vector of X .

$$y - e \quad X^T e = 0$$

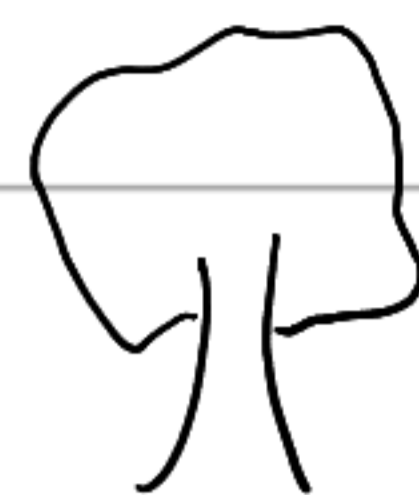
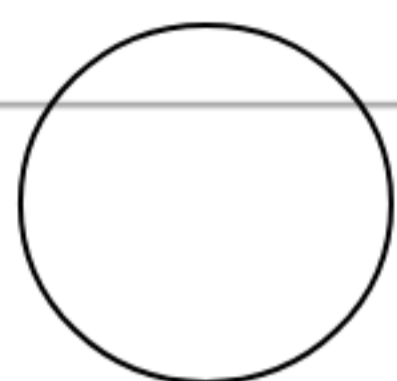
suppose $y - e = X \hat{w}$ thus we have.

$$X^T (y - X \hat{w}) = 0.$$

$$X^T X \hat{w} = X^T y$$

Classification and support vector machine.

classify

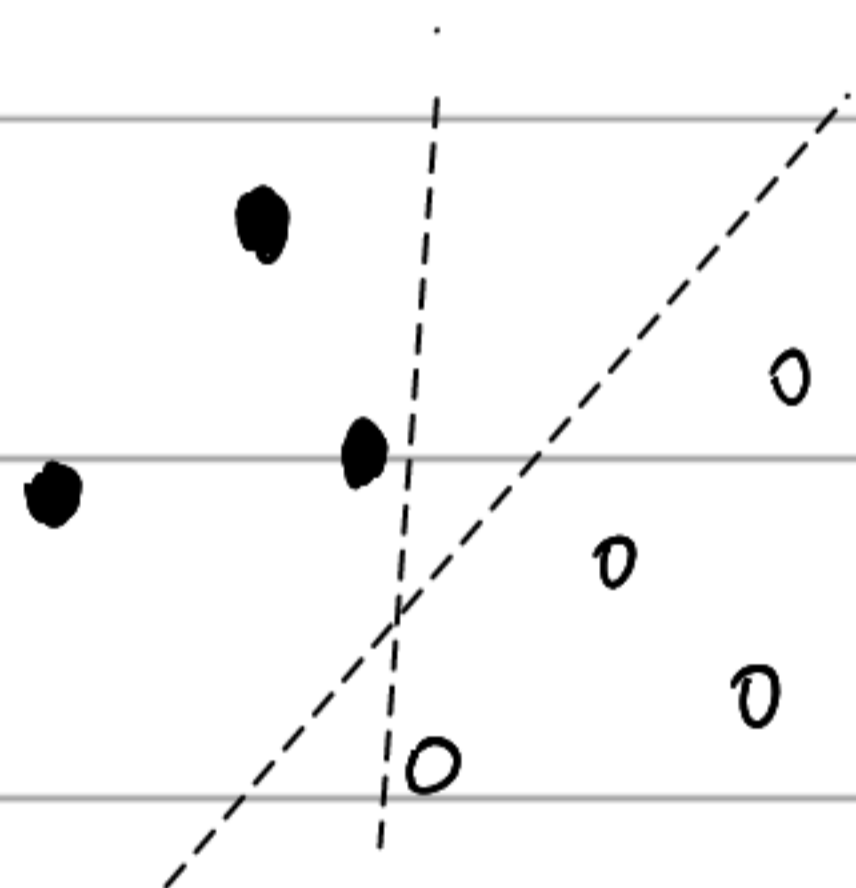


given m data points $(x_1, y_1) \dots (x_m, y_m)$.

classifier is a function s.t.

$$\begin{cases} f(x_i) > 0 & \text{iff } y_i = +1 \\ f(x_i) < 0 & \text{iff } y_i = -1 \end{cases} \iff y_i f(x_i) > 0.$$

linear classifier: $f(x) = w^T x + b$.



which one is better?

maximize the minimum distance to the hyper plane. ^{against noise}

Support vector machine: linear classifier with max margin

$$\max_{w, b} \min_{1 \leq i \leq m} \frac{|w^T x_i + b|}{\|w\|}$$

$$\text{s.t. } y_i (w^T x_i + b) > 0.$$

since $y_i = \text{sgn}(w^T x_i + b)$. $|w^T x_i + b| = y_i (w^T x_i + b)$.

$\forall \alpha > 0$. $\tilde{w} = \alpha w$. $\tilde{b} = \alpha b$ also feasible.

choosing α properly. s.t. $\min_{1 \leq i \leq m} y_i (\tilde{w}^T x_i + \tilde{b}) = 1.$

$$\max \frac{1}{\|w\|}$$

$$\text{s.t. } y_i (\tilde{w}^T x_i + \tilde{b}) \geq 1.$$

which is equivalent to .

$$\min \frac{1}{2} \|\tilde{w}\|^2$$

$$\text{s.t. } y_i (\tilde{w}^T x_i + \tilde{b}) \geq 1.$$

Global optima and local optima.

$$\min_{x \in X} f(x). \quad \text{let } x^* \triangleq \operatorname{argmin}_{x \in X} f(x).$$

x^* is a global minimum if $f(x^*) \leq f(x)$

global maximum.

global optima may not exist.

$$- f(x) = x. \quad X = \mathbb{R}. \quad \inf f(x) = -\infty.$$

$$- f(x) = \frac{1}{x} \quad X = \mathbb{R}_{>0} \quad \inf f(x) = 0.$$

When will global optima exist?

Continuous functions on compact sets have global optima.