

Lecture 3. Analysis on normed linear space (II)

saddle point. 鞍点.

interior point. 内点. boundary point 边界

$$\exists \varepsilon > 0. \downarrow B(x, \varepsilon) \triangleq \{y : \|x - y\| < \varepsilon\} \subseteq X.$$

First-order necessary condition. 有偏导不够. $f(x, y) = \begin{cases} \frac{xy}{x^2 + y^2} \\ 0 \end{cases}$

if $f(x^*)$ local minimum. f differentiable at x^* .

for any feasible direction v . $(\exists \varepsilon > 0. \forall 0 < \delta < \varepsilon. x^* + \delta v \in X)$

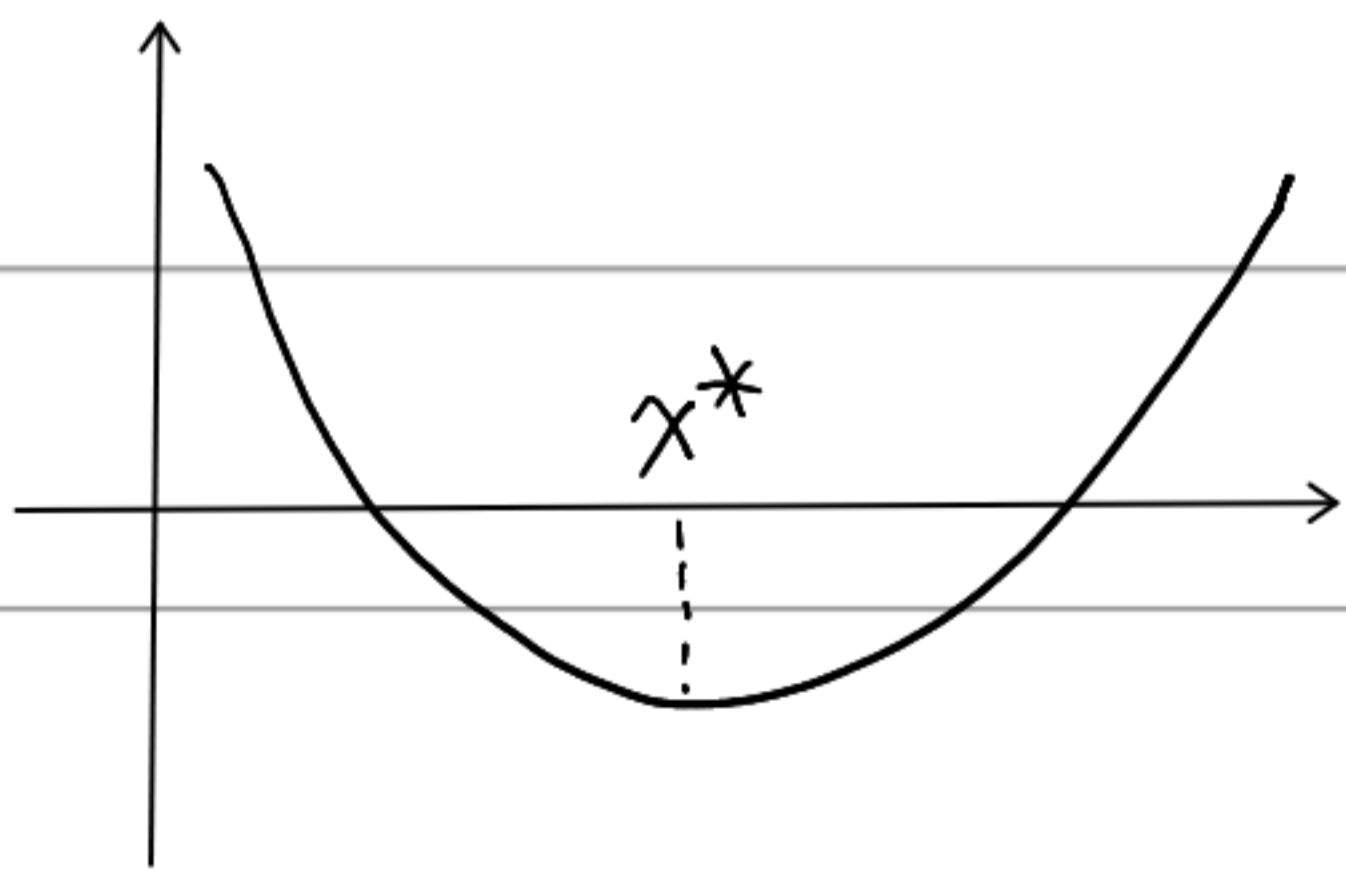
$$v^T \nabla f(x^*) \geq 0.$$

Cor. if x^* interior. $\nabla f(x^*) = 0$

有方向导数不够
 $f(x, y) = \begin{cases} \frac{y^2}{x} & x \neq 0 \\ 0 & x = 0 \end{cases}$
 偏导连续.

However, this condition does not suffice.

$$f(x) = x^3. \quad f(x_1, x_2) = x_1^2 - x_2^2. \quad f(x_1, x_2) = x_1^3 - x_2^3.$$



$$x \uparrow x^* : f(x) \downarrow \quad f'(x) < 0.$$

$$x \downarrow x^* : f(x) \downarrow \quad f'(x) > 0.$$

$$f''(x) > 0 \quad ?$$

Second order partial derivative. $\frac{\partial^2 f}{\partial x_i \partial x_j}(x_0)$

因此 $f: \mathbb{R}^n \rightarrow \mathbb{R}$.
 that's why we

Hessian matrix. denoted by $\nabla^2 f(x)$.

introduce Jacobian.

Hessian is given by $[\nabla^2 f(x_0)]_{ij} = \frac{\partial^2 f(x_0)}{\partial x_i \partial x_j}$.

if $\frac{\partial f}{\partial x_i \partial x_j}$ and $\frac{\partial f}{\partial x_j \partial x_i}$ exists in $B(x, \epsilon)$.

and continuous at x_0 . then $\frac{\partial f}{\partial x_i \partial x_j} = \frac{\partial f}{\partial x_j \partial x_i}$.

Cor. Hessian is a symmetric matrix.

Taylor expansion (second order).

$$f(x_0 + \delta) = f(x_0) + \delta f'(x_0) + \frac{\delta^2}{2} f''(x_0) + o(\delta^2).$$

$$f(\vec{x}_0 + \vec{\delta}) = f(\vec{x}_0) + \nabla f(\vec{x}_0)^T \vec{\delta} + o(\|\delta\|).$$

$$f(\vec{x}_0 + \vec{\delta}) = f(\vec{x}_0) + \nabla f(\vec{x}_0)^T \vec{\delta} + \frac{1}{2} \vec{\delta}^T \nabla^2 f(\vec{x}_0) \vec{\delta} + o(\|\delta\|^2)$$

or expansion.

$$f(\vec{x}_0 + \vec{\delta}) = f(\vec{x}_0) + \sum_{i=1}^n \frac{\partial f}{\partial x_i}(\vec{x}_0) \delta_i + \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \frac{\partial^2 f}{\partial x_i \partial x_j}(\vec{x}_0) \delta_i \delta_j + o(\delta^2)$$

Example. $f(x) = w^T x + b$. $\nabla f(x) = w$ $\nabla^2 f(x) = 0$.

$$f(x) = x^T A x \quad \nabla f(x) = (A + A^T) x \quad \nabla^2 f(x) = A + A^T$$

in particular. if A symmetric. $\nabla f(x) = 2Ax$. $\nabla^2 f(x) = 2A$.

verify it: $f(x_0 + \delta) = (x_0 + \delta)^T A (x_0 + \delta) = x_0^T A x_0 + \delta^T A x_0 + x_0^T A \delta + \delta^T A \delta$
 $= f(x_0) + (x_0^T A + x_0^T A^T) \delta + \delta^T A \delta$

Taylor: $f(x_0 + \delta) = f(x_0) + (Ax_0 + A^T x_0)^T \delta + \frac{1}{2} \delta^T (A + A^T) \delta + o(\|\delta\|^2)$.

Chain rule for Hessian.

$$h(x) = g(f(x)) \quad Dh(x) = Dg(f(x)) \cdot Df(x)$$

if $h: \mathbb{R}^n \rightarrow \mathbb{R}^m$. $Dh: \mathbb{R}^n \rightarrow \mathbb{R}^{m \times n}$ what is D^2h ?

$$h(x): \mathbb{R}^n \rightarrow \mathbb{R}. \quad g(x): \mathbb{R}^n \rightarrow \mathbb{R}. \quad f(x) = Ax + b$$

$$\nabla h(x) = \nabla g(f(x)) \cdot A = 0.$$

$$\begin{aligned} \nabla^2 h(x) &= \nabla g(f(x)) \cdot DA + A^T D(\nabla g(f(x))) \\ &= A^T \nabla^2 g(f(x)) A. \end{aligned}$$

In particular. $g(t) = f(x_0 + tv)$ $\nabla^2 g(t) = v^T \nabla^2 f(x_0 + tv) v^T$.

if $f(x_0)$ is a local minimum. we know $\nabla f(x_0) = 0$

$$f(x_0 + \delta) \geq f(x_0) \Rightarrow \delta^T \nabla^2 f(x_0 + \delta) \delta \geq 0.$$

Definite matrix.

忽略小项

Second-order necessary condition

Semi definite . positive semidefinite if

$$A^T = A \quad (\text{symmetric}) \quad \forall x. \quad x^T A x \geq 0$$

positive definite if symmetric and $\forall x \neq 0 \quad x^T A x > 0$

negative if ≤ 0 (semidefinite) < 0 (definite)

indefinite if $x_1^T A x_1 < 0 < x_2^T A x_2$

Remark. $x^T A x$ quadratic form = 次型

$$x^T A x = x^T A^T x = x^T \left(\frac{1}{2} (A + A^T) \right) x$$

Properties of definiteness.

- $A \geq 0$ (semidefinite) iff all eigenvalues $\lambda \geq 0$.

- $A > 0$ (definite) iff all eigenvalues $\lambda > 0$

$$A = \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix} \quad x = (a, b)^T.$$

$$a^2 + b^2 + (a-b)^2$$

$$x^T A x = (2a - b, -a + 2b) \begin{pmatrix} a \\ b \end{pmatrix} = 2a^2 - ab - ab + 2b^2 \geq 0.$$

$$\det(\lambda I - A) = (\lambda - 2)^2 - 1 = 0 \Rightarrow \lambda = 1, 3.$$

why? $A = U \Lambda U^T = \sum_{i=1}^n \lambda_i v_i v_i^T$

$$U = (v_1, v_2, \dots, v_n) \quad \Lambda = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n).$$

$$x^T A x = (U^T x)^T \Lambda (U^T x) = \sum_{i=1}^n \lambda_i \|v_i x\|^2.$$

$$x = \sum_{i=1}^n y_i v_i \quad x^T A x = \sum_{i=1}^n \lambda_i \|y_i v_i\|^2.$$

Proof of $\delta^T \nabla^2 f(x_0) \delta \geq 0$:

otherwise $\exists \lambda < 0$. ^{let} v be the eigenvector with respect to λ .

$$\begin{aligned} f(x_0 + tv) &= f(x_0) + \nabla f(x_0)^T (tv) + \frac{1}{2} (tv)^T \nabla^2 f(x_0) (tv) + o(\|tv\|^2) \\ &= f(x_0) + \frac{\lambda}{2} t^2 \|v\|^2 + o(t^2 \|v\|^2). \end{aligned}$$

